SMOOTH MANIFOLDS FALL 2023 - HOMEWORK 2

SOLUTIONS

Problem 1. Consider the transformation group $\Gamma = \{R_{k\pi/2} : k \in \mathbb{Z}\}$, where $R_{\theta} : \mathbb{R}^2 \to \mathbb{R}^2$ is the linear transformation determined by the matrix $R_{\theta} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$. Show that the quotient space \mathbb{R}^2/Γ is a topological manifold. Is it homeomorphic to a familiar one? Furthermore, does it have a smooth structure such that the map $\pi : \mathbb{R}^2 \to \mathbb{R}^2/\Gamma$ is a submersion? Does there exist a smooth structure such that π is C^{∞} ? Justify your answers through pictures and "moral" arguments: do not write formal proofs.

Solution. Come talk to me in office hours and we can draw some fun pictures!

Problem 2. Let $\mathbb{T}^2 = \mathbb{R}^2/\mathbb{Z}^2$ be the 2-torus, and assume that $D \subset \mathbb{T}^2$ is a discrete subgroup. Show that \mathbb{T}^2/D is diffeomorphic to \mathbb{T}^2 . [*Hint*: Show that the lift of D to \mathbb{R}^2 is also a discrete subgroup containing \mathbb{Z}^2 . You may use the fact that all discrete subgroups of \mathbb{R}^2 are isomorphic to $\{0\}$ \mathbb{Z} , and \mathbb{Z}^2 .]

Solution. Let $D \subset \mathbb{T}^2$ is a discrete subgroup and $\pi : \mathbb{R}^2 \to \mathbb{T}^2$ be the factor map (ie, the map which assigns to a vector v its coset $[v] = v + \mathbb{Z}^2 \subset \mathbb{R}^2$. Since D is both discrete and compact (being a subset of a compact space), it is finite. Then $\tilde{D} = \pi^{-1}(D)$ is also a discrete subgroup, since if \tilde{D} accumulated at a point in \mathbb{R}^2 , $D = \pi(\tilde{D})$ would have an accumulation point as well. Furthermore, it is a compact extension of $\mathbb{Z}^2 = \pi^{-1}(0)$ since D is finite. It is also torsion-free, since it is a subgroup of \mathbb{R}^2 . Therefore, by the classification of finite rank abelian groups, it must be isomorphic to \mathbb{Z}^2 itself. Choose generators v_1 and v_2 for \tilde{D} , and let $L : \mathbb{R}^2 \to \mathbb{R}^2$ be the map $L(t, s) = tv_1 + sv_2$. Then $L(\mathbb{Z}^2) = \tilde{D}$ by construction. We claim that L induces a diffeomorphism between $\mathbb{R}^2/\mathbb{Z}^2$ and $\mathbb{R}^2/\tilde{D} = \mathbb{T}^2/D$.

Indeed, the map $\overline{L}(v + \mathbb{Z}^2) = L(v) + \widetilde{D}$ is well-defined, since a different representative of v in \mathbb{T}^2 must differ by an element of \mathbb{Z}^2 , which is taken to an element of \widetilde{D} by L. Furthermore, since the local charts for \mathbb{T}^2 are constructed by lifting a neighborhood to \mathbb{R}^2 , and similarly for $\mathbb{T}^2/\widetilde{D}$, in the canonical local charts on \mathbb{R}^2 (which are just given by the identity), the map is linear, and hence C^{∞} .

Problem 3. Let $\varphi : U \to \mathbb{R}^n$ be a smooth chart for a smooth manifold M. Define a corresponding set $\hat{U} = \bigcup_{p \in U} T_p M \subset TM$, and let an element of \hat{U} be denoted by v_p , where p denotes the basepoint of the vector v. Define $\hat{\varphi} : \hat{U} \to \mathbb{R}^n \times \mathbb{R}^n$ by

$$\hat{\varphi}(v_p) = (\varphi(p), v_{p,\varphi}),$$

where $v_{p,\varphi} \in T_p^{\varphi}M := T_{\varphi(p)}\mathbb{R}^n = \mathbb{R}^n$ is the vector v as represented in the chart φ (recall that T_pM is isomorphic to each $T_p^{\varphi}M$ for any chart φ whose domain contains p). Show that if \mathcal{A} is a smooth atlas of charts for M, then $\hat{\mathcal{A}} = \left\{ (\hat{U}, \hat{\varphi}) : (U, \varphi) \in \mathcal{A} \right\}$ is a smooth atlas on TM (this is the smooth atlas on TM induced by \mathcal{A}).

Solution. We use the notations as described in the problem. To show that the collection $\hat{\mathcal{A}}$ forms a smooth atlas for TM, the transition maps are C^{∞} . First, notice that \hat{U} and \hat{V} intersect if and only if U and V intersect on M, since if a vector lies in the intersection, its base point must lie in both U and V. Let $(\hat{U}, \hat{\varphi})$ and $(\hat{V}, \hat{\psi})$ be charts for TM and $W = U \cap V$. Then consider the map $\hat{\varphi} \circ \hat{\psi}^{-1} : \hat{\psi}(W) \to \mathbb{R}^n \times \mathbb{R}^n$. We compute the derivative of $\hat{\varphi}$ directly. Notice that moving the vector component does not change the basepoint, so the derivative by moving along the n coordinates does not change the first n. However, the derivative by moving along first n coordinates can change both the position on the output, as well as the vectors. Indeed, the total derivative is the block matrix:

$$D(\hat{\varphi} \circ \hat{\psi}^{-1}) = \begin{pmatrix} D(\varphi \circ \psi^{-1}) & \mathbf{0} \\ A & D(\varphi \circ \psi^{-1}) \end{pmatrix}$$

where each block is an $n \times n$ matrix, and A is the matrix of second derivatives $A_{ij} = \frac{\partial D(\varphi \circ \psi^{-1})_{ij}}{\partial x_i}$ since it measures how much the (i, j)th component derivative changes as the base component moves. This map is locally invertible, and hence a diffeomorphism, since its derivative is a block lower triangular matrix with invertible diagonal blocks, and hence invertible.

Remark 1. We have only discussed C^{∞} structures, but you can talk about manifolds with C^{r} -structures, with $r \geq 1$. You can imagine what the definition is. In this setting, C^{r} -manifolds have a canonical C^{r-1} -structure on TM. Of course, when $r = \infty$, $r - 1 = \infty$ as well.

Problem 4. Show that if $U \subset \mathbb{R}^k$ is open, $\varphi : U \to \mathbb{R}^n$ is C^{∞} and $d\varphi(x)$ is injective, then there exists a C^{∞} change of coordinates diffeomorphism $H : \mathbb{R}^n \to \mathbb{R}^n$ defined near $\varphi(x)$ such that $H \circ \varphi$ takes values in $\mathbb{R}^k \subset \mathbb{R}^n$.

Solution. Let $E \subset \mathbb{R}^n$ denote the image of $d\varphi(x) : \mathbb{R}^k \to \mathbb{R}^n$. By injectivity, $\dim(E) = k$. Let $L : \mathbb{R}^{n-k} \to \mathbb{R}^n$ be any linear map such that \mathbb{R}^n is the direct sum of E and the image of L. Define $F : \mathbb{R}^n \to \mathbb{R}^n$ by $F(x, y) = \varphi(x) + Ly$, where $(x, y) \in \mathbb{R}^n$ is written componentwise with $x \in \mathbb{R}^k$ and $y \in \mathbb{R}^{n-k}$. Notice that

$$DF(x, y) = (d\varphi(x) L)$$

So that the image of DF(x,0) is the sum of the images of $d\varphi(x)$ and L, which is all of \mathbb{R}^n . Hence DF(x,y) is an isomorphism, and there exists open neighborhoods in \mathbb{R}^n for which F has an inverse. Let $H : \mathbb{R}^n \to \mathbb{R}^n$ denote the inverse of F. Then $(x,0) = H(F(x,0)) = H(\varphi(x) + L \cdot 0) = H \circ \varphi(x)$.

Problem 5. Let M be a C^{∞} manifold, $k \in \mathbb{N}$ and $X \subset M$ be a closed, connected subset such that for every $x \in X$, there exists $U \subset \mathbb{R}^k$ and an embedding $\varphi : U \to M$ such that the image of φ is an open neighborhood of x in X. Show that X has a C^{∞} manifold structure such that the inclusion of X into M is an embedding. [*Hint*: Use the previous problem!]

Proof. Since M is a closed connected subset of a manifold, it is second countable and Hausdorff. By assumption is locally Euclidean (the charts are the inverses of the maps φ . So we must verify the transition maps are C^{∞} . Let φ and ψ denote the inverses of maps provided in the assumption of the problem, $U_{\varphi}, U_{\psi} \subset X$ denote their domains (open subsets of $X \subset M$) and $V_{\varphi}, V_{\psi} \mathbb{R}^k$ denote their ranges. Let $x \in U_{\varphi} \cap U_{\psi}$, and choose a C^{∞} chart of x for $M, \eta : U_{\eta} \to V_{\eta}$, so that $U_{\eta} \subset M$ is open and $V_{\eta} \subset \mathbb{R}^n$ is open.

We begin by restricting maps appropriately. Indeed, notice that $U_{\varphi} \cap U_{\psi}$ is an open in X. It is therefore the intersection of an open neighborhood of M with X. By intersecting it with U_{η} , we may assume that it is in fact equal to U_{η} . In summary, to study differentiability properties at x, we may assume that $U_{\varphi} = U_{\psi} = U_{\eta} \cap X$.

Observe that $\eta \circ \varphi^{-1}$ is a C^{∞} map defined locally from \mathbb{R}^k to \mathbb{R}^n and since φ^{-1} is an embedding, $d(\eta \circ \varphi^{-1})$ is injective at $\varphi(x)$. Hence, by the previous problem, we may replace η by $H \circ \eta$ and assume that image of $\eta \circ \varphi^{-1}$ is contained in $\mathbb{R}^k \times \{0\}$. However, since we assume that ψ and φ have the same domain, ψ^{-1} and φ^{-1} have the same image. Hence $\eta \circ \psi^{-1}$ must also be contained in $\mathbb{R}^k \times \{0\}$.

Finally, note that since $\eta \circ \varphi^{-1}$ and $\eta \circ \psi^{-1}$ are full rank, C^{∞} maps from open subsets of \mathbb{R}^k to open subsets of $\mathbb{R}^k \times \{0\} \cong \mathbb{R}^k$, they have local inverses by the inverse function theorem. Therefore, $\varphi \circ \psi^{-1} = (\eta \circ \varphi^{-1})^{-1} \circ (\eta \circ \psi^{-1})$ is a local C^{∞} diffeomorphism at $\psi(x)$.